

Internal resonance and nonlinear response of an axially moving beam: two numerical techniques

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Abstract. The nonlinear resonant response of an axially moving beam is investigated in this paper via two different numerical techniques: the pseudo-arclength continuation technique and direct time integration. In particular, the response is examined for the system in the neighborhood of a three-to-one internal resonance between the first two modes as well as for the case where it is not. The equation of motion is reduced into a set of nonlinear ordinary differential equation via the Galerkin technique. This set is solved using the pseudo-arclength continuation technique and the results are confirmed through use of direct time integration. Vibration characteristics of the system are presented in the form of frequency-response curves, time histories, phase-plane diagrams, and fast Fourier transforms (FFTs).

Keywords: axially moving beams; vibrations; stability; bifurcation; internal resonance

1. Introduction

The demand for structural elements such as beams (Ghayesh 2011, Ghayesh *et al.* 2011, Ghayesh *et al.* 2011, Darabi *et al.* 2012, Ghayesh 2012, Ghayesh *et al.* 2012, Ghayesh *et al.* 2012), plates (Amabili *et al.* 2006, Amabili 2010, Amabili and Carra 2012) and shells is continuously increasing, largely due to their growing application in industry. Among these structural elements, axially moving systems arise in a large class of mechanical, industrial, and automotive applications. Textile fibers, paper sheets, band saw blades, robot arms, conveyor belts, and magnetic tapes are just a few examples. These widespread applications motivated a substantial amount of research in this area.

As reviewed by Wickert and Mote (Wickert and Mote 1988) and later by Chen (2005), dynamics of axially moving systems has been studied extensively in literature. One such example is (Naguleswaran and Williams 1968, Shih 1971, Simpson 1973, Holmes 1978, Thurman and Mote 1969). However, a thorough literature review on this topic will not be undertaken in this paper (interested readers are referred to Wickert and Mote (1988) and Chen (2005)).

These early studies were pursued and extended by: Chen and co-workers (Tang *et al.* 2009, Chen and Chen 2010, Chen and Ding 2010, Huang *et al.* 2011, Yang *et al.* 2012), who considered string and different beam models of the system and employed different analytical and numerical methods; Marynowski and co-workers (Marynowski and Kapitaniak 2002, Marynowski and Kapitaniak 2007),

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who considered several energy dissipation mechanisms in the model; Pellicano and Vestroni (Pellicano and Vestroni 2002), who investigated the dynamics of high-speed axially moving systems; Suweken and Van Horssen (Suweken and Van Horssen 2003), who investigated the vibrations of the system with weak nonlinearity and found several internal resonances in the system dynamics; Huang *et al.* (2011), who employed the method of harmonic balance to investigate the system dynamics; Pakdemirli and co-workers (Pakdemirli *et al.* 1994, Pakdemirli and Ulsoy 1997, Pakdemirli and Özkaya 1998, Öz *et al.* 2001, Pakdemirli and Boyaci 2003, Burak Özhan and Pakdemirli 2010), who conducted systematic research in this area by employing some perturbation techniques; Stylianou and Tabarrok (Stylianou and Tabarrok 1994), who used the finite element method to examine the system dynamics; and Nguyen and Hong (2011), who developed a novel control algorithm to suppress the transverse vibrations of an axially moving web.

Recently, further investigations on this topic have been conducted by the first author and co-workers (Ghayesh and Khadem 2007, Ghayesh 2008, Ghayesh 2009, Ghayesh 2010, Ghayesh and Balar 2010, Ghayesh *et al.* 2010, Ghayesh 2011a, Ghayesh 2011b, Ghayesh and Moradian 2011, Ghayesh 2012a, Ghayesh 2012b, Ghayesh 2012c, Ghayesh and Amabili 2012, Ghayesh *et al.* 2012, Ghayesh *et al.* 2012, Ghayesh *et al.* 2012, Kazemirad *et al.* 2012). These analyses involved various system models such as strings and Euler-Bernoulli, Rayleigh, and Timoshenko beam models. The effect of a partial foundation on the system dynamics was investigated in (Ghayesh 2008, Ghayesh 2009). The dynamics of the system made of laminated composite materials were investigated in (Ghayesh *et al.* 2010).

In the present study, the *sub-critical* resonant response of an axially moving beam possessing a three-to-one internal resonance between the first two modes is obtained using the pseudo-arclength continuation technique and direct time integration; a higher order discretization is conducted so as to study *modal interactions* and *internal resonances* as well as to obtain fairly *accurate* results. The analysis also includes the case without internal resonances between the first two modes. The results are presented in the form of frequency-response curves, time histories, phase-plane portraits, and fast Fourier transforms (FFTs). It is shown that the results obtained from the above two methods are in excellent agreement.

2. Equation of motion and methods of solution

As shown in Fig. 1, consider a simply supported axially moving beam of length L , constant density ρ , cross-sectional area A and Young's modulus E which is traveling at a constant axial speed V . There are two forces to be considered, namely P and $\hat{F}(\hat{x}, \tau) = \hat{F}(\hat{x})\cos(\omega\tau)$; the former being a pretension and the latter a harmonic transverse force distributed along the entire length of the beam. Furthermore, \hat{x} denotes a Lagrangian coordinate.

The dimensionless form of the equation of motion of this system has been given previously in (Huang *et al.* 2011) as follows

$$\frac{\partial^2 w}{\partial \tau^2} + 2v \frac{\partial^2 w}{\partial x \partial \tau} + (v^2 - 1) \frac{\partial^2 w}{\partial x^2} + v_f^2 \frac{\partial^4 w}{\partial x^4} = \frac{3}{2} v_1^2 \left(\frac{\partial w}{\partial x} \right)^2 \frac{\partial^2 w}{\partial x^2} + F(x) \cos(\Omega \tau) \quad (1)$$

in which

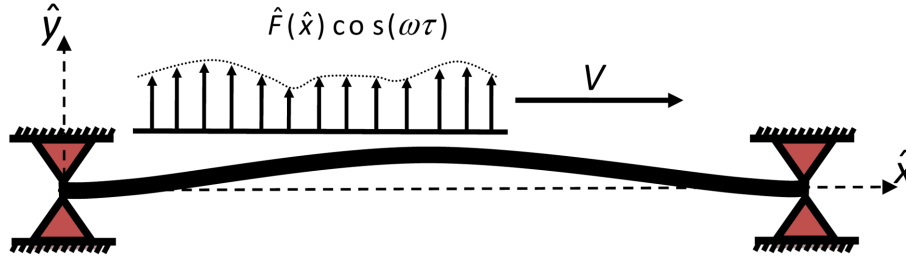


Fig. 1 Schematic representation of an axially moving beam subjected to a transverse distributed harmonic excitation force

$$\begin{aligned}
 x &= \frac{\hat{x}}{L}, w = \frac{\hat{w}}{L}, t = \tau \sqrt{\frac{P}{\rho AL^2}}, v = V \sqrt{\frac{\rho A}{P}} \\
 v_1 &= \sqrt{\frac{EA}{P}}, v_f = \sqrt{\frac{EI}{PL^2}}, F = \frac{\hat{F}L}{P}, \Omega = \omega \sqrt{\frac{\rho AL^2}{P}}
 \end{aligned} \quad (2)$$

where x denotes the dimensionless counterpart of \hat{x} ; w and \hat{w} represent the dimensionless and dimensional transverse displacements; τ and t represent the dimensional and dimensionless time; F denotes the dimensionless forcing amplitude; and Ω is the dimensionless excitation frequency. Eq. (1) has been derived under the following assumptions: (i) rotatory inertia and shear deformations are neglected; (ii) only the transverse displacement is considered (Marynowski and Kapitaniak 2002, Ghayesh 2010, Huang *et al.* 2011); (iii) the type of nonlinearity is geometric; (iv) the beam has a uniform cross-section; (v) the relation between the curvature and the displacement is assumed to be linear; (vi) the nonlinearity is due to the stretching effect of the mid-plane of the beam; (vii) the equation is truncated at third order.

Exciting only the first mode by $f_1\phi_1(x)$, where $\phi_1(x)$ is the first eigenfunction for the transverse vibrations of a hinged-hinged stationary beam, as well as employing the well-known Galerkin method for Eq. (1) results in

$$\begin{aligned}
 \sum_{j=1}^N \left(\int_0^1 \phi_i \phi_j dx \right) \ddot{q}_j + 2v \sum_{j=1}^N \left(\int_0^1 \phi_i \phi_j dx \right) \dot{q}_j + (v^2 - 1) \sum_{j=1}^N \left(\int_0^1 \phi_i \phi_j'' dx \right) q_j \\
 + v_f^2 \left(\sum_{j=1}^N \int_0^1 \phi_i \phi_j''' dx \right) q_j = \frac{3}{2} v_1^2 \left(\sum_{j=1}^N \sum_{k=1}^N \sum_{l=1}^N \phi_i \phi_j'' \phi_k' \phi_l' dx \right) q_j q_k q_l \\
 + \int_0^1 \phi_i f_1 \phi_1 dx \cos \Omega t, \text{ for } i = 1, 2, 3, \dots, N
 \end{aligned} \quad (3)$$

where $\phi_i(x)$ is the i th eigenfunction of a hinged-hinged beam; dot and prime denote the differentiation with respect to dimensionless time and axial coordinate, respectively. Eq. (3) forms a set of second order nonlinear ordinary differential equations; however, most numerical techniques can best handle first order ordinary differential equations. Therefore, Eq. (3) is transformed into a set of first order nonlinear ordinary differential equations via $y_i = \dot{q}_i$ for $i = 1, 2, \dots, N$, yielding $2N$ first order nonlinear ordinary differential equations. In this paper, twelve ($N=6$) first order nonlinear ordinary differential equations with coupled terms are solved using the AUTO code (Doedel *et al.* 1998), which uses the pseudo-arclength continuation method. Direct time integration

is conducted using a variable step-size Runge-Kutta method to validate the results obtained via the pseudo-arclength continuation technique. It should also be noted that although there is no damping in the equation of motion, the numerical simulations include a simple viscous damping with the dimensionless coefficient of μ .

3. Resonant response of the system possessing a three-to-one internal resonance between the first two modes

In this section, the resonant response of the system with a three-to-one internal resonance is examined. Two cases with different damping coefficients are considered, and it is shown that the damping of the system may change the system dynamics substantially. The frequency-response curves of the system are first plotted using the pseudo-arclength continuation technique, and then several points on those curves are tested via direct time integration.

The following parameters have been selected in the analysis of the first case: $\nu = 0.6$, $\nu_f = 0.173$, $\nu_1 = 33.526$, $\mu = 0.07$, $f_1 = 0.0055$. The system with the first two numerical values given above undergoes a three-to-one internal resonance between the first two modes. Solving the linear part of Eq. (3) gives the following linear natural frequencies for the first two modes: $\omega_1 = 2.8172$ and $\omega_2 = 8.4984$ ($\omega_2 \approx 3\omega_1$) confirms that a three-to-one internal resonance occurs. The (maximum) amplitude of oscillation of this system in the neighborhood of the fundamental natural frequency is shown in Fig. 2; q_1 and q_2 are the first and second generalized coordinates. The curves have been obtained using the pseudo-arclength continuation technique and the symbols (with white filling) have been obtained by direct time integration. Theoretically, as the excitation frequency is increased, the bent section of the curve corresponding to the first generalized coordinate is to the right, showing hardening-type nonlinearity. As seen in Fig. 2(a), theoretically, as the excitation frequency is increased from $\Omega = 0.6\omega_1$, the q_1 amplitude increases accordingly until point A ($\Omega = 1.0648\omega_1$), where stability is lost via a limit point bifurcation. The amplitude of this unstable solution decreases until point B ($\Omega = 1.0620\omega_1$), where stability is

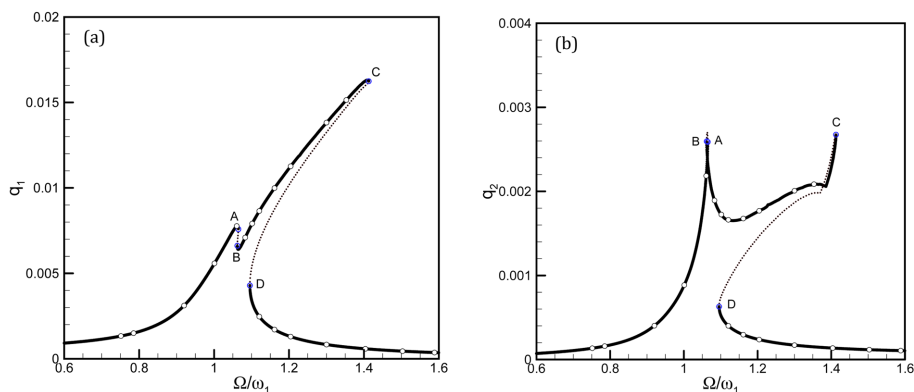


Fig. 2 The frequency-response curve of the system with $\mu = 0.07$ possessing a three-to-one internal resonance between the first two modes, i.e., $\omega_2 \approx 3\omega_1$: (a) the amplitude of the first generalized coordinate and (b) the amplitude of the second generalized coordinate. Bold and dotted lines represent the stable and unstable solutions, respectively. Symbols with white filling show the results obtained from direct time integration, and the blue symbols show the bifurcation points

regained; the energy is transferred from the first generalized coordinate to the second one. Increasing the excitation frequency causes the q_1 amplitude to increase until point C ($\Omega = 1.4127\omega_1$) is hit, where the motion becomes unstable once again by means of a limit point bifurcation. As the excitation frequency is decreased, this now unstable solution regains its stability at point D ($\Omega =$

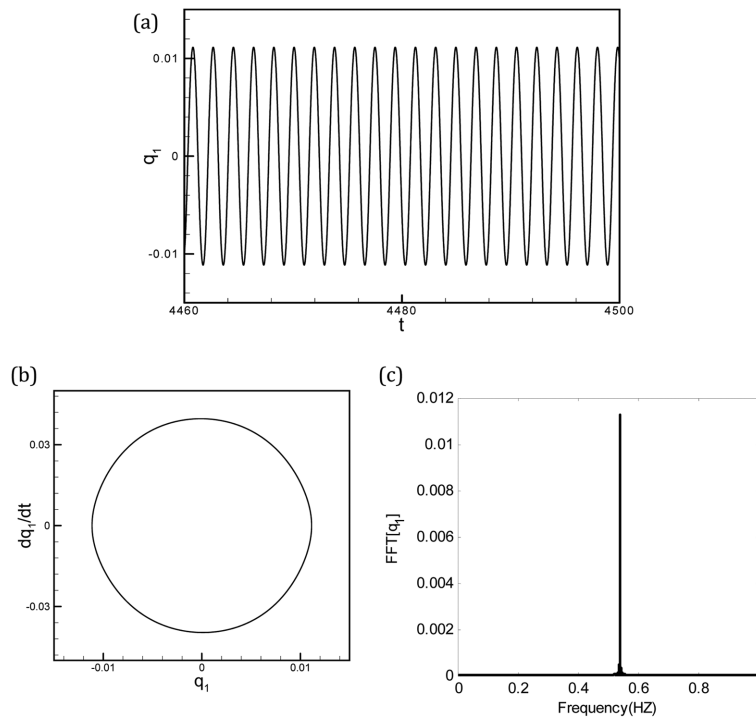


Fig. 3 Periodic oscillations of the system of Fig. 2 at $\Omega = 1.2\omega_1$: (a) the time history, (b) phase-plane diagrams, and (c) FFT of the q_1 motion

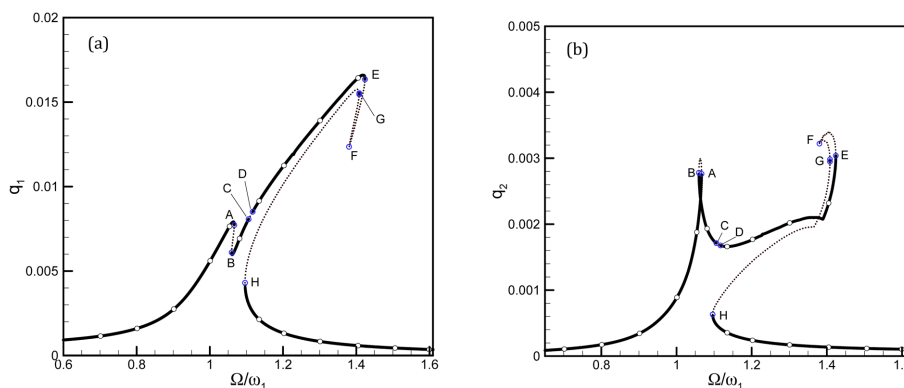


Fig. 4 The frequency-response curve of the system with $\mu = 0.045$ possessing a three-to-one internal resonance between the first two modes, i.e., $\omega_2 \approx 3\omega_1$: (a) the amplitude of the first generalized coordinate and (b) the amplitude of the second generalized coordinate. Bold and dotted lines represent the stable and unstable solutions, respectively. Symbols with white filling show the results obtained from direct time integration, and the blue symbols show the bifurcation points

$1.0956\omega_1$) and maintains it until $\Omega = 1.6\omega_1$. Typical features of a periodic motion at $\Omega = 1.2\omega_1$ are shown in Fig. 3. It is also seen in Fig. 2 that the only type of bifurcation is limit point; there is no torus bifurcation.

The second case to be considered is similar to the first, having almost all of the same parameters, except a lower damping coefficient (i.e., $\mu = 0.045$). The frequency response of this case is shown in Fig. 4. As seen in this figure, hardening nonlinearity is present, and both the numerical results are in agreement. As seen in Fig. 4(a), theoretically, increasing the excitation frequency causes the q_1 amplitude, which is stable, to increase accordingly until the first limit point at point A ($\Omega = 1.0667\omega_1$) is reached. By slightly decreasing the excitation frequency, the response becomes unstable and lasts until the second limit point at B ($\Omega = 1.0595\omega_1$), where the stability is regained. As the excitation

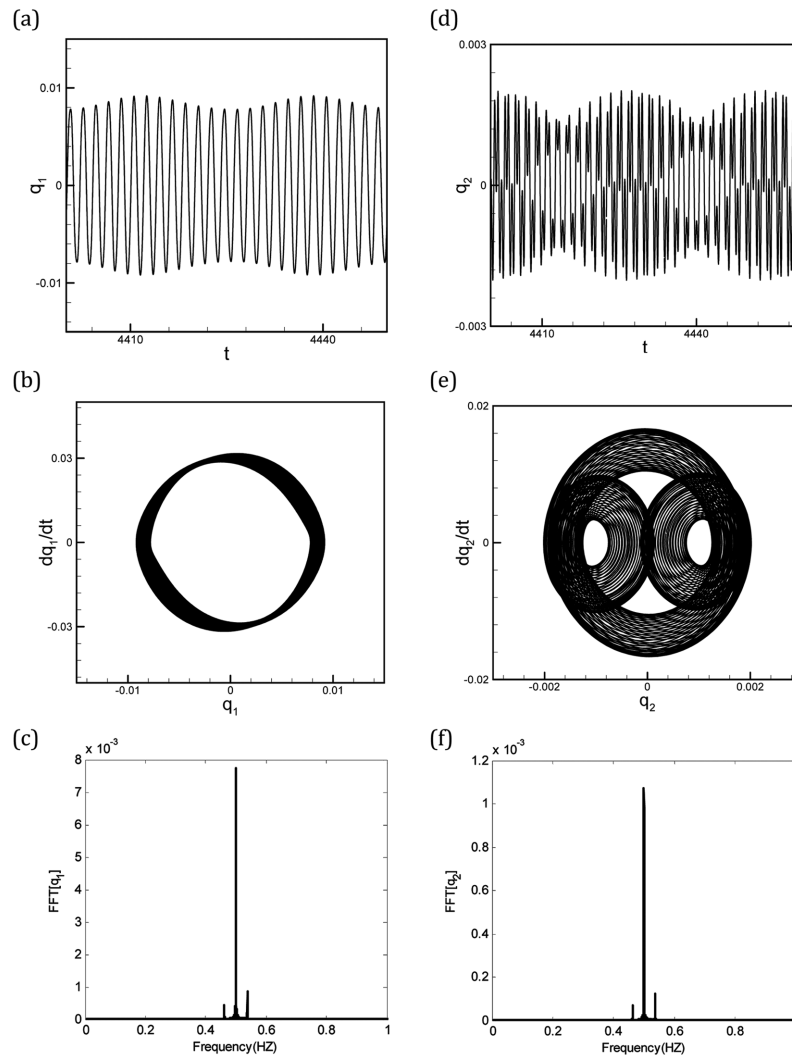


Fig. 5 Quasiperiodic oscillations of the system of Fig. 4 at $\Omega = 1.115031\omega_1$: (a) the time history, (b) phase-plane diagram and (c) FFT of the q_1 motion; (d-f) the same characteristics of (a-c) of the q_2 motion

frequency is increased further, the stability of the periodic response is lost at point C ($\Omega = 1.1058\omega_1$), via a torus bifurcation. The stability is regained at point D ($\Omega = 1.1170\omega_1$) via the second torus bifurcation. In the frequency range between points C and D , the periodic solution is unstable, implying that there might be another type of motion present, such as quasiperiodic or chaotic. Figs. 5(a)-(c) shows (a) the time history of the q_1 motion, (b) the phase-plane portrait for the q_1 motion, (c) the FFT of the q_1 motion at $\Omega = 1.115031\omega_1$ - Figs. 5(d)-(f) shows the same characteristics of Figs. 5(a)-(c) for the q_2 motion. As seen in this figure, the amplitudes are modulated and the response is *quasiperiodic*. As the excitation frequency is increased further (Fig. 4(a)), the stability is lost once again at point E ($\Omega = 1.4238\omega_1$) via a limit point bifurcation. There is another limit point bifurcation at point F ($\Omega = 1.3802\omega_1$). In the vicinity of point G ($\Omega \approx 1.4082\omega_1$) the stability is initially regained but lost very soon afterward. This unstable solution lasts until point H ($\Omega = 1.0961\omega_1$) is reached, where the motion becomes stable via a limit point bifurcation. It is important to note that, as opposed to the previous case (Fig. 2), torus bifurcations and quasiperiodic oscillations are observed in the dynamical behavior of the system with $\mu = 0.045$ (see Figs. 4 and 5; compare Figs. 2 and 4).

4. Resonant response of the system with no internal resonances between the first two modes

The frequency-response curve of the system for the first generalized coordinate, with the following dimensionless parameters $\nu = 0.2$, $\nu_f = 0.173$, $\nu_1 = 33.526$, $\mu = 0.06$, $f_1 = 0.0055$ is shown in Fig. 6. With these parameters, the first linear natural frequency is determined as: $\omega_1 = 3.4932$. As shown in this figure, the nonlinearity type is hardening; it was found that, theoretically, as the excitation frequency is increased from $\Omega = 0.6\omega_1$, the q_1 amplitude increases accordingly until the first limit point at point A ($\Omega = 1.3673\omega_1$) is hit, where it loses stability. The stability is regained via the

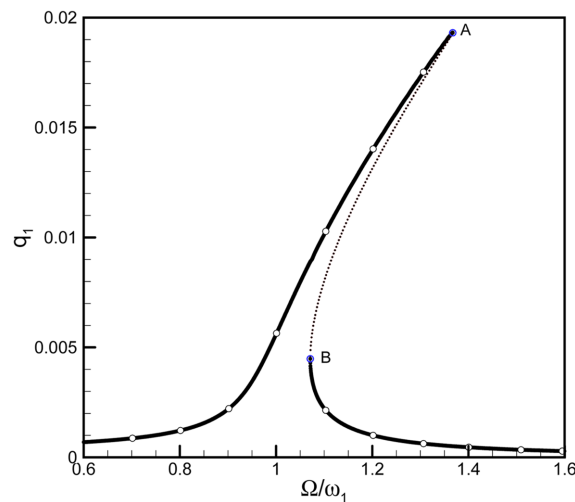


Fig. 6 The frequency-response curve of the system without any internal resonances between the first two modes. Bold and dotted lines represent the stable and unstable solutions, respectively. Symbols with white filling show the results obtained from direct time integration, and the blue symbols show the bifurcation points

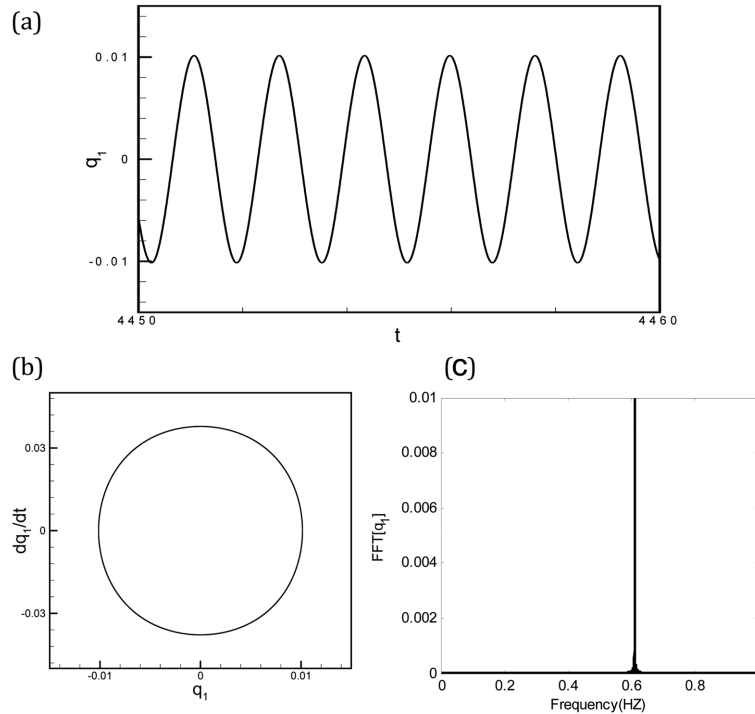


Fig. 7 Periodic oscillations of the system of Fig. 6 at $\Omega = 1.1\omega_1$: (a) the time history, (b) phase-plane diagram, and (c) FFT of the q_1 motion

second limit point bifurcation at point B , where $\Omega = 1.0711\omega_1$. This now stable solution lasts until $\Omega = 1.6\omega_1$. Since the system is away from internal resonances between the first two modes, there is no energy transferred from the first mode to the second. Limit point bifurcation is the only type of bifurcation that is observed in the dynamical behavior of the system. Typical vibration characteristic of the system for $\Omega = 1.1\omega_1$ are shown in Fig. 7.

5. Conclusions

The transverse, nonlinear resonant response of an axially moving beam possessing a three-to-one internal resonance between the first two modes as well as the case without any internal resonance between the first two modes have been investigated numerically. The pseudo-arclength continuation technique was used to plot the frequency-response curves. The stable solution branches were validated using direct time integration. The vibration characteristics of the system in the range, beyond the first torus bifurcation and before the second one were examined and it was shown that the system displays a quasiperiodic motion. The typical characteristics of this quasiperiodic motion were investigated via time histories, phase-plane plots, and FFTs. It was shown that the results obtained from both numerical techniques are in excellent agreement. This study contributed to the current knowledge on this topic by detecting new phenomena such as the occurrence of torus bifurcations in the system dynamics, which are hard to detect analytically.

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